

## Symmetry Groups:

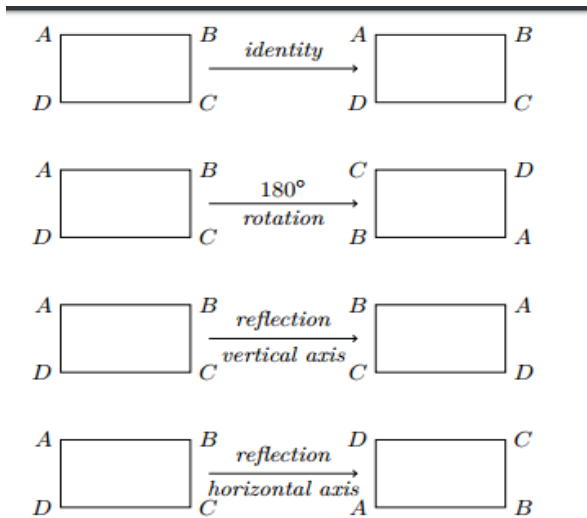


Figure 3.5: Rigid motions of a rectangle

- A symmetry of a geometric figure is a rearrangement of the figure which preserves the shape

- A map from the plane to itself preserving the symmetry of an object is called a rigid motion.

↑  
sometimes just say symmetry as well.

Find all symmetries of an Equilateral triangle.

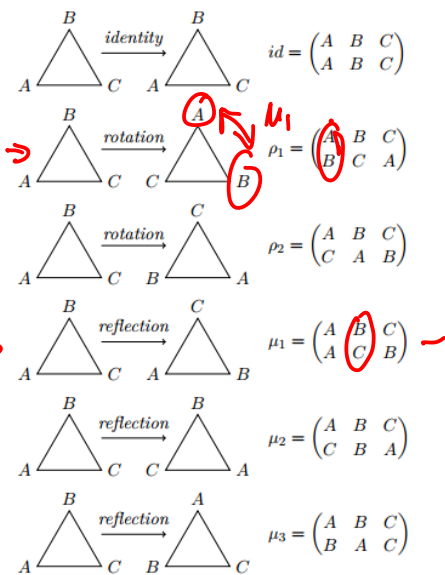


Figure 3.6: Symmetries of a triangle

Recall: a permutation of a set  $S$  is a 1-1 and onto map  $\pi: S \rightarrow S$

- 3 vertices  $\Rightarrow 3! = 6$  permutations

$\therefore$  Triangle has at most 6 symmetries

- Natural Question: what happens if we "multiply" or "compose" symmetries?  
Ex) what is  $\mu_1 \circ \mu_1 = \mu_2$  (Apply  $\mu_1$  then apply  $\mu_1$ )

$$\mu_1(\mu_1(A)) = \mu_1(B) = C$$

$$\mu_1 \circ \mu_1 = \begin{pmatrix} A & B & C \\ C & B & A \end{pmatrix} = \mu_2$$

Trying this with  $\mu_1 \circ \mu_1 = \mu_3 \neq \mu_1 \circ \mu_1$

$\circ$	id	$\rho_1$	$\rho_2$	$\mu_1$	$\mu_2$	$\mu_3$
id	id	$\rho_1$	$\rho_2$	$\mu_1$	$\mu_2$	$\mu_3$
$\rho_1$	$\rho_1$	$\rho_2$	id	$\mu_3$	$\mu_1$	$\mu_2$
$\rho_2$	$\rho_2$	id	$\rho_1$	$\mu_2$	$\mu_3$	$\mu_1$
$\mu_1$	$\mu_1$	$\mu_2$	$\mu_3$	id	$\rho_1$	$\rho_2$
$\mu_2$	$\mu_2$	$\mu_3$	$\mu_1$	$\rho_2$	id	$\rho_1$
$\mu_3$	$\mu_3$	$\mu_1$	$\mu_2$	$\rho_1$	$\rho_2$	id

This is a group

Table 3.7: Symmetries of an equilateral triangle

## Formal Definition of a Group

A binary operation or law of composition on a set  $G$  is a function  $G \times G \rightarrow G$  that assigns to each pair  $(a, b) \in G \times G$  a unique element  $a \cdot b$  or  $ab$  or  $a \circ b$  or  $a + b$  called the composition of  $a$  and  $b$ .

A group  $(G, \cdot)$  is a set  $G$  together with a binary operation  $(a, b) \mapsto a \cdot b$  that satisfies the following axioms

- The binary operation is associative. That is

$$(a \cdot b) \cdot c = a \cdot (b \cdot c)$$

for any  $a, b \in G$

- There exist an element  $e \in G$  called the identity element such that  $\forall a \in G$

$$e \cdot a = a \cdot e = a$$

- For each element  $a \in G$  there exist an inverse element in  $G$  denoted  $a^{-1}$ , such that

$$a \cdot a^{-1} = a^{-1} \cdot a = e.$$

Note that  $a \cdot b \neq b \cdot a$  in general

A group  $G$  s.t.  $a \cdot b = b \cdot a \quad \forall a, b \in G$  is called a abelian or commutative group.

### Examples

-  $(\mathbb{Z}_n, +)$  is a Group

$$\mathbb{Z}_n = \{0, 1, \dots, n-1\}$$

-  $\mathbb{Z}_n$  is not a group with multiplication. Note  $\mathbb{Z}_n \setminus \{0\}$  may not be a group either i.e.  $2 \in \mathbb{Z}_6$

$$1 \cdot 2 = 2$$

$$2 \cdot 2 = 4$$

$$3 \cdot 2 = 0$$

$$4 \cdot 2 = 2$$

$$5 \cdot 2 = 4$$

things with a multiplicative inverse

Group of units of  $\mathbb{Z}_n$

$$- U(n) = \{ k \in \mathbb{Z}_n \mid \gcd(k, n) = 1 \}$$

Ex |  $U(8)$

$\cdot$	1	3	5	7
1	1	3	5	7
3	3	1	7	5
5	5	7	1	3
7	7	5	3	1

Table 3.12: Multiplication table for  $U(8)$

# A matrix Group

$$GL_2(\mathbb{R}) = \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \mid \det(A) \neq 0, a, b, c, d \in \mathbb{R} \right\}$$



$$\left\{ \text{A } 2 \times 2 \text{ Real matrix} \mid \text{A is invertible} \right\}$$

$GL_2(\mathbb{R})$  is a group under matrix multiplication.

To see why:

- Matrix mult. is associative

-  $I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \in GL_2(\mathbb{R})$  is the identity

· i.e.  $IA = AI = A$  for all  $A \in GL_2(\mathbb{R})$

- The product of two invertible matrices is invertible  
(since  $\det(A \cdot B) = \det(A) \cdot \det(B)$ )  
or  $(AB)^{-1} = B^{-1}A^{-1}$ )

- Inverses exist  $\forall A \in GL_2(\mathbb{R})$  that is

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} = \frac{1}{ad-bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

$\therefore GL_2(\mathbb{R})$  is a Group

~ Note  $GL_2(\mathbb{R})$  is not commutative

**Example 3.15.** Let

$$1 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad I = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$
$$J = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix} \quad K = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix},$$

where  $i^2 = -1$ . Then the relations  $I^2 = J^2 = K^2 = -1$ ,  $IJ = K$ ,  $JK = I$ ,  $KI = J$ ,  $JI = -K$ ,  $KJ = -I$ , and  $IK = -J$  hold. The set  $Q_8 = \{\pm 1, \pm I, \pm J, \pm K\}$  is a group called the *quaternion group*. Notice that  $Q_8$  is noncommutative.